

Mechanism Design

1: Definitions, Implementation

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This slide deck:

- 1 Defining a Mechanism
- 2 Revelation Principle
- 3 Dominant Strategy Implementation
- 4 Bayesian Implementation

What is a mechanism?

Let's reverse engineer from a simpler question: **What is a game?**

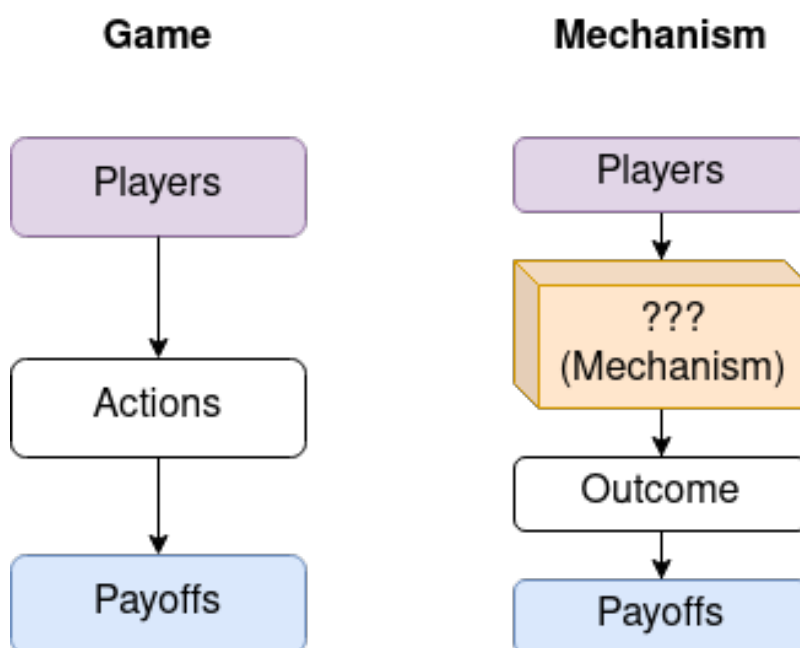
- 1 Set of players $i \in \{1, \dots, N\}$
- 2 Set of actions A_i for every i ; set of action profiles $A \equiv \times_{i \in N} A_i$
- 3 Collection of utility functions $u_i : A \rightarrow \mathbb{R}$

(This is a *normal-form game*. All extensive-form games ("trees") and incomplete-information games can be represented as normal-form games.)

Which parts of this definition are fixed at a higher level, and which can we *design* as a part of a *mechanism*?

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Problem environment



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General Problem Set-up

In our MD problem, the following environment will be **fixed**:

- N agents,
- set X of **outcomes**,
- each agent i has **type** $\theta_i \in \Theta_i$:
 - describes agent's **information**,
 - describes agent's **preferences**;
- the type profile $\theta = (\theta_1, \dots, \theta_N)$ is distributed according to a distribution F with p.d.f. ϕ ,
 - (often a missing subscript denotes a vector of respective objects)
 - distribution F is commonly known and agreed upon
- each agent has a **utility** function $u_i(x, \theta_i)$ that depends on the collective choice $x \in X$ and his type θ_i ,

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Mechanism

- a mechanism is a game played by the agents
- each agent has an action set A_i in this game

Definition (mechanism)

A **mechanism** $\Gamma = (A_1, \dots, A_N, g(\cdot))$ is a collection of:

- N **strategy sets** (A_1, \dots, A_N) and
- an **outcome function** $g : A_1 \times \dots \times A_N \rightarrow X$.

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Social Choice Function

Definition (Social choice function)

A **social choice function** is a function $f : \Theta_1 \times \cdots \times \Theta_N \rightarrow X$ that assigns to each profile of types $(\theta_1, \dots, \theta_N)$ a collective choice $f(\theta_1, \dots, \theta_N) \in X$.

- gives a desired outcome as a function of the agents' types

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Implementation

Definition (implementation)

Mechanism $\Gamma = (A_1, \dots, A_N, g(\cdot))$ **implements** the s.c.f. f if there is **an equilibrium** strategy profile (a_1^*, \dots, a_N^*) of the Bayesian game induced by Γ **such that**

$$g(a_1^*(\theta_1), \dots, a_N^*(\theta_N)) = f(\theta_1, \dots, \theta_N)$$

for all $(\theta_1, \dots, \theta_N) \in \Theta_1 \times \cdots \times \Theta_N$.

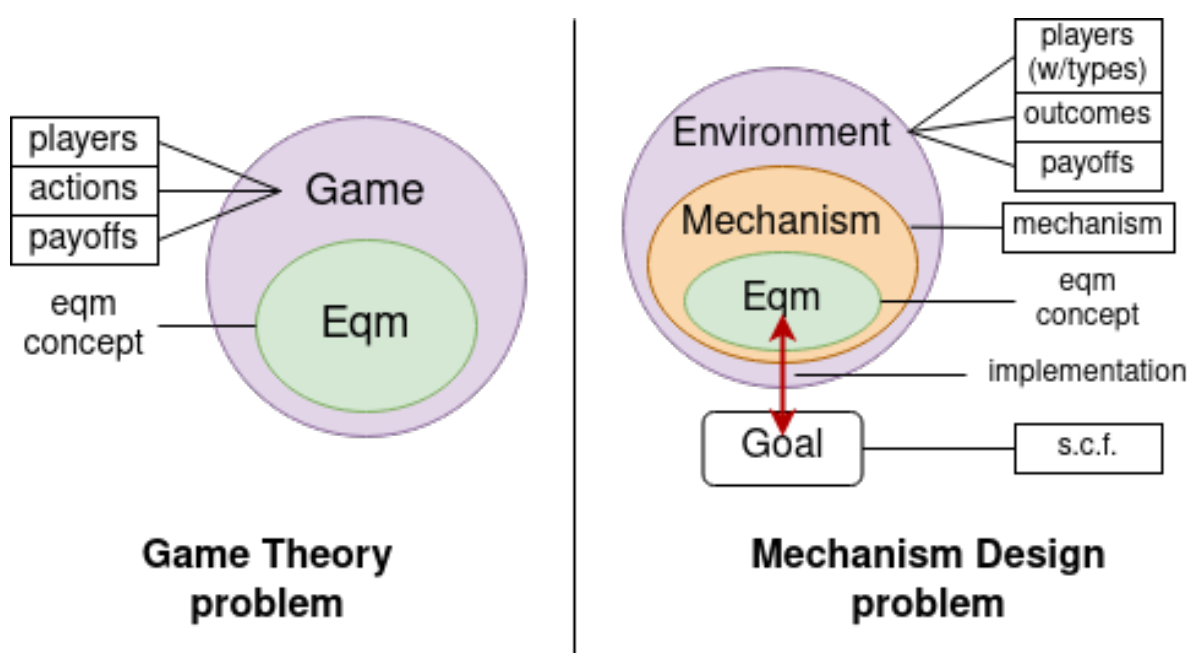
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Summary of definitions

- S.c.f. f describes what we want to achieve;
- Mechanism $\Gamma = (S, g)$ describes what we do and how;
- Implementability says whether we have achieved our goal.

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Full problem setup



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Revelation Principle

- Main cheat in Mechanism Design! No need to brute force through uncountable numbers of different games! It is enough to just... (click to see more)
- Instead of making players play the game, ask them for their θ_i and promise to play on their behalf!
- Requires that the designer has commitment power.
 - Strong assumption, sometimes reasonable(?)
 - The necessary evil for our purposes.
 - Useful for formal analysis, but in the end the resulting mechanism can *sometimes* work even without commitment.

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Revelation Principle: Definitions

Fix some s.c.f. $f : \Theta \rightarrow X$.

Definition (Direct revelation mechanism)

A **direct revelation mechanism** for f is a mechanism in which $A_i = \Theta_i$ for all i and $g(\theta) = f(\theta)$

Definition (Truthful implementation)

S.c.f. f is **truthfully implementable** if it can be implemented by a direct revelation mechanism.

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Revelation Principle: Statement

Revelation principle (blanket statement)

Suppose there exists a mechanism $\Gamma = (A_1, \dots, A_N, g)$ that implements the social choice function f .

Then f is **truthfully implementable**.

- The “theorem” above is informal.
 - “Implementation” requires “an equilibrium”, which can mean a million different things.
 - We will now plug in some specific equilibrium concepts.

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Game Theory Recap: Dominant Strategy

- strategy a_i is a full contingent plan of play
- strategy a_i is **dominant** for agent i if it is best *no matter what the other players do*

Definition (dominant strategy)

Given mechanism $\Gamma = (A, g)$, $a_i : \Theta_i \rightarrow A_i$ is a **dominant strategy** if for all $\theta_i \in \Theta_i$

$$u_i(g(a_i(\theta_i), a_{-i}), \theta_i) \geq u_i(g(\hat{a}_i, a_{-i}), \theta_i)$$

for all $\hat{a}_i \in A_i$ and all $a_{-i} \in A_{-i}$.

- our definition slightly different from the standard – does not require strict inequality

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Dominant Strategy Equilibrium

- in a **dominant strategy equilibrium** every player plays a dominant strategy

Definition (dominant strategy equilibrium)

A strategy profile (a_1^*, \dots, a_N^*) is a **dominant strategy equilibrium** of mechanism $\Gamma = (A_1, \dots, A_N, g)$ if for all i and all $\theta_i \in \Theta_i$

$$u_i(g(a_i^*(\theta_i), a_{-i}), \theta_i) \geq u_i(g(\hat{a}_i, a_{-i}), \theta_i)$$

for all $\hat{a}_i \in A_i$ and all $a_{-i} \in A_{-i}$.

Now let's finally be formal about all our definitions.

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Dominant Strategy Implementation

- A mechanism **implements f in dominant strategies** if
 - the game induced by the mechanism has a dominant strategy equilibrium
 - the outcome in this equilibrium coincides with f

Definition (implementation in dominant strategies)

A mechanism $\Gamma = (A_1, \dots, A_N, g)$ **implements** the social choice function f **in dominant strategies** if there exists a dominant strategy equilibrium (a_1^*, \dots, a_N^*) of Γ such that $g(a_1^*(\theta_1), \dots, a_N^*(\theta_N)) = f(\theta)$ for all $\theta \in \Theta$.

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Good Implementation Concept?

- very robust equilibrium concept
 - no need to predict what the other players will play
 - no need to know the type distribution ϕ
 - works even if
 - players don't know ϕ or even if players believe in different ϕ_i (protects from players' model misspecification)
 - players think that other players are not rational
- not a panacea
 - does not rule out other weird Nash Equilibria (example: second-price auction)
 - is not necessarily collusion-proof
 - does not protect from designer's model misspecification

Bottom line: it's as good as they get, but far from perfect.

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Dominant Strategy Incentive Compatibility

Theorem (Revelation Principle for Dominant Strategies)

Suppose there exists a mechanism $\Gamma = (A_1, \dots, A_N, g)$ that implements the social choice function f in dominant strategies.

Then f is truthfully implementable in dominant strategies.

Definition (Dominant Strategy Incentive Compatibility)

" f is dominant strategy incentive compatible (DSIC)"

means the exact same thing as

" f is truthfully implementable in dominant strategies".

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DS Revelation Principle: Proof

Let Γ implement f in dominant strategies, i.e. there is a strategy profile (a_1^*, \dots, a_N^*) such that $g(a_1^*(\theta_1), \dots, a_N^*(\theta_N)) = f(\theta)$ for all θ , and for all i and $\theta_i \in \Theta_i$,

$$u_i(g(a_i^*(\theta_i), a_{-i}), \theta_i) \geq u_i(g(\hat{a}_i, a_{-i}), \theta_i)$$

for all $\hat{a}_i \in A_i$ and all $a_{-i} \in A_{-i}$.

Then

$$u_i(g(a_i^*(\theta_i), a_{-i}^*(\theta_{-i})), \theta_i) \geq u_i(g(a_i^*(\hat{\theta}_i), a_{-i}^*(\theta_{-i})), \theta_i)$$

for all $\hat{\theta}_i \in \Theta_i$, $\theta_{-i} \in \Theta_{-i}$.

Since $g(a^*(\theta)) = f(\theta)$,

$$u_i(f(\theta_i, \hat{\theta}_{-i}), \theta_i) \geq u_i(f(\hat{\theta}_i, \hat{\theta}_{-i}), \theta_i)$$

for all $\hat{\theta}_{-i} \in \Theta_{-i}$.

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Revelation Principle: Is it cool or is it cool?

- Idea: to solve the problem **mathematically**, it is enough to only look at **direct mechanisms**!
 - This result allows to quickly check whether a given f is [DS] implementable.
 - If yes, gives you a mechanism to implement it.
 - If not, helps you describe a set of implementable s.c.f. and pick second best.
 - *Yours today for ~~only \$49.99 + shipping~~ FREE with a qualifying Mechanism Design course!*
- Translating that solution to **the real world** may (and often does) result in an **indirect mechanism**! We'll see some examples.

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DSIC vs BIC

- We've looked at DS implementation so far. Robust but demanding. Can we get more mileage by relaxing the equilibrium notion?
- Now: use standard [Bayes-Nash Equilibrium](#) as solution concept. Weaker equilibrium concept, so:
 - we are less confident it will produce the intended outcome, but
 - it can implement more(?) s.c.f.-ns.
 - (there's a literature studying whether sets of DSIC and BIC s.c.f.-ns are equal in special settings)

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Bayesian Implementation

Start with the **general model** as before:

- N agents;
- set of alternatives X ;
- type $\theta_i \in \Theta_i$ is private information of i ;
- common prior belief $\phi \in \Delta(\Theta)$ about distribution of types;
- utility functions $u_i(x, \theta_i)$;
- each agent uses Bayes' rule to form a belief over other agents' types

$$\phi(\theta_{-i}|\theta_i) = \phi(\theta_i, \theta_{-i}|\theta_i) = \frac{\phi(\theta_i, \theta_{-i})}{\int_{\tilde{\theta}_{-i} \in \Theta_{-i}} \phi(\theta_i, \tilde{\theta}_{-i}) d\tilde{\theta}_{-i}}.$$

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Bayes-Nash Equilibrium

Definition (Bayes-Nash equilibrium)

The **strategy profile** $a^* = (a_1^*, \dots, a_N^*)$ with $a_i^* : \Theta_i \rightarrow A_i$ is a **Bayes-Nash equilibrium** of the mechanism $\Gamma = (A_1, \dots, A_N, g)$ if, for all i and all $\theta_i \in \Theta_i$,

$$\mathbb{E}_{\theta_{-i}} [u_i(g(a_i^*(\theta_i), a_{-i}^*(\theta_{-i})), \theta_i) | \theta_i] \geq \mathbb{E}_{\theta_{-i}} [u_i(g(\hat{a}_i, a_{-i}^*(\theta_{-i})), \theta_i) | \theta_i]$$

for all $\hat{a}_i \in A_i$.

- Standard NE reasoning: if everyone else plays eqm strats, i has no incentive to deviate.
- (This definition is for pure strategies, but there is no problem in allowing mixed strategies.)
- Expectations are taken w.r.t. distribution $F(\theta)$

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Bayesian Implementation

Definition (Bayesian implementation)

Mechanism $\Gamma = (A_1, \dots, A_N, g)$ **implements s.c.f. f in Bayes-Nash equilibrium** if there is a BNE $a^* = (a_1^*, \dots, a_N^*)$ of Γ such that $f(\theta) = g(a^*(\theta))$ for all $\theta \in \Theta$.

Definition (Bayesian implementability)

S.c.f. f is implementable in BNE if there exists Γ which implements it in BNE.

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Truthful Bayesian Implementation

Definition (Truthful Bayesian implementation)

S.c.f. f is truthfully implementable in BNE (=Bayesian Incentive Compatible, **BIC**) if $a_i^*(\theta_i) = \theta_i$ is a BNE of the direct revelation mechanism $\Gamma = (\Theta_1, \dots, \Theta_N, f)$.

That is, for all i, θ_i , and $\hat{\theta}_i \in \Theta_i$,

$$\mathbb{E}_{\theta_{-i}} [u_i(f(\theta_i, \theta_{-i}), \theta_i) | \theta_i] \geq \mathbb{E}_{\theta_{-i}} [u_i(f(\hat{\theta}_i, \theta_{-i}), \theta_i) | \theta_i].$$

Every player is asked for their type; reporting truthfully is a BNE.

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Revelation principle

Theorem (Revelation principle for Bayes-Nash equilibrium)

If there exists a mechanism $\Gamma = (A_1, \dots, A_N, g)$ that implements f in BNE, then f is truthfully implementable in BNE.

The proof is pretty much the same as for DSIC.