Mechanism Design

1: Definitions, Implementation

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This slide deck:

What is a mechanism?

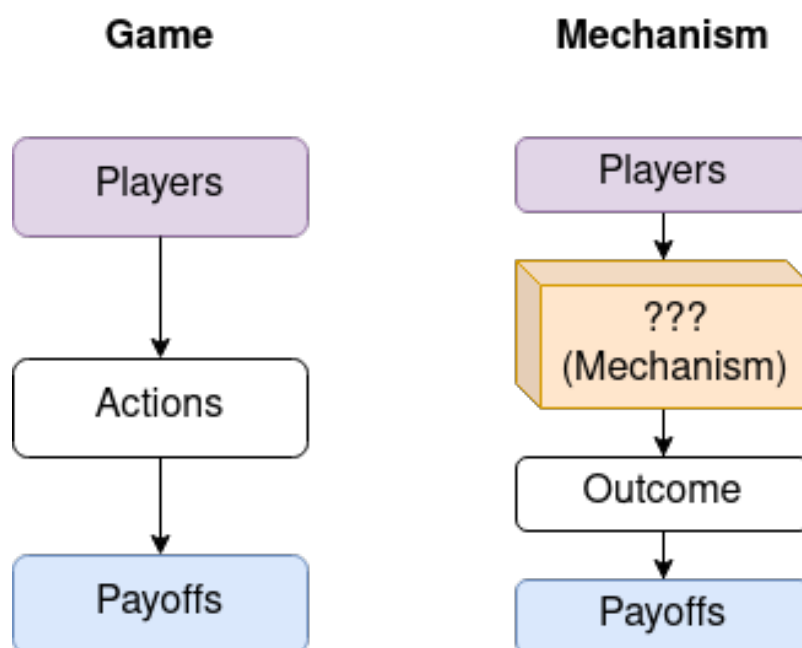Let's reverse engineer from a simpler question: **What is a game?**

1. Set of players $i \in \{1, ..., N\}$

2. Set of actions A_i for every i; set of action profiles $A \equiv \times_{i \in N} A_i$

3. Collection of utility functions $u_i : A \to \mathbb{R}$

(This is a *normal-form game*. All extensive-form games ("trees") and incomplete-information games can be represented as normal-form games.)

Which parts of this definition are fixed at a higher level, and which can we *design* as a part of a *mechanism*?

Problem environment

General Problem Set-up

In our MD problem, the following environment will be **fixed**:

- N agents,

- set X of outcomes,

- each agent i has type $\theta_i \in \Theta_i$:

  - describes agent's information,

  - describes agent's preferences;

- the type profile $\theta = (\theta_1, \ldots, \theta_N)$ is distributed according to a distribution F with p.d.f. ϕ,

  - (often a missing subscript denotes a vector of respective objects)

  - distribution F is commonly known and agreed upon

- each agent has a utility function $u_i(x, \theta_i)$ that depends on the collective choice $x \in X$ and his type θ_i,

Mechanism

- a mechanism is a game played by the agents

- each agent has an action set A_i in this game

Definition (mechanism)

A mechanism $\Gamma = (A_1, \ldots, A_N, g(\cdot))$ is a collection of:
- N strategy sets $(A_1, \ldots, A_N)$ and
- an outcome function $g : A_1 \times \cdots \times A_N \to X$.

Social Choice Function

Definition (Social choice function)

A social choice function is a function $f : \Theta_1 \times \cdots \times \Theta_N \to X$ that assigns to each profile of types $(\theta_1, \ldots, \theta_N)$ a collective choice $f(\theta_1, \ldots, \theta_N) \in X$.

- gives a desired outcome as a function of the agents' types

Implementation

Definition (implementation)

Mechanism $\Gamma = (A_1, \ldots, A_N, g(\cdot))$ implements the s.c.f. f if there is an equilibrium strategy profile $(a_1^*, \ldots, a_N^*)$ of the Bayesian game induced by Γ such that

$$g(a_1^*(\theta_1), \ldots, a_N^*(\theta_N)) = f(\theta_1, \ldots, \theta_N)$$

for all $(\theta_1, \ldots, \theta_N) \in \Theta_1 \times \cdots \times \Theta_N$.
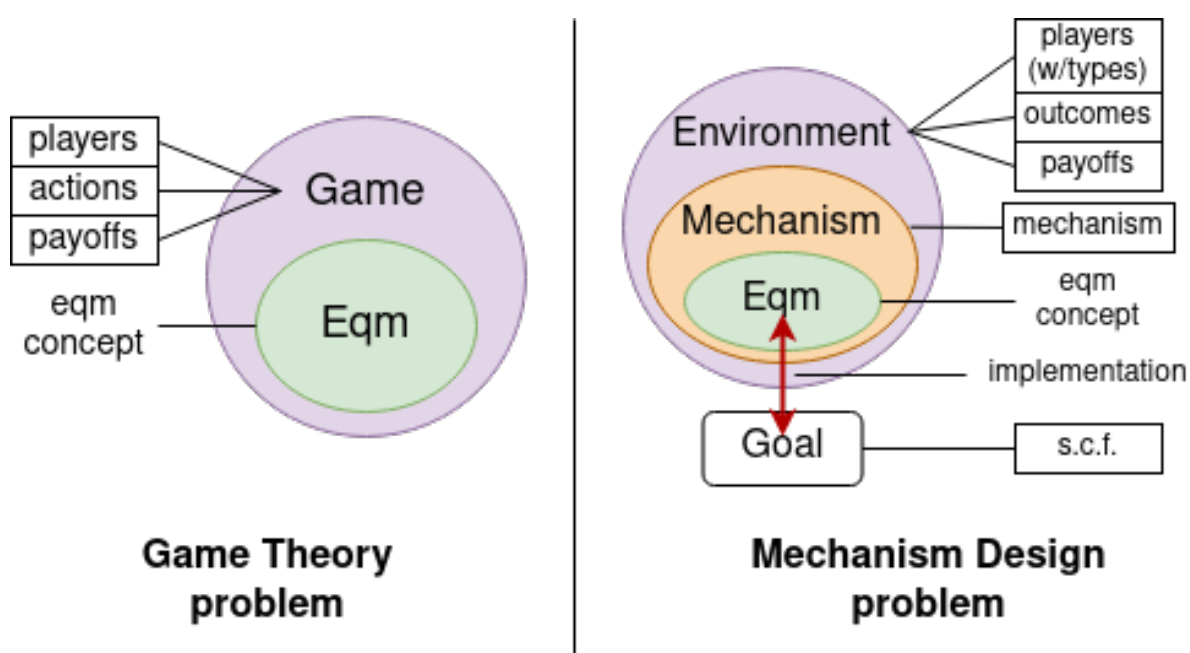
Summary of definitions

- S.c.f. f describes what we want to achieve;

- Mechanism $\Gamma = (S, g)$ describes what we do and how;

- Implementability says whether we have achieved our goal.

Full problem setup

This slide deck:

Revelation Principle

- Main cheat in Mechanism Design! No need to bruteforce through uncountable numbers of different games! It is enough to just... (click to see more)

- Instead of making players play the game, ask them for their θ_i and promise to play on their behalf!

- Requires that the designer has commitment power.

  - Strong assumption, sometimes reasonable(?)

  - The necessary evil for our purposes.

  - Useful for formal analysis, but in the end the resulting mechanism can *sometimes* work even without commitment.

Revelation Principle: Definitions

Fix some s.c.f. $f : \Theta \to X$.

Definition (Direct revelation mechanism)

A direct revelation mechanism for f is a mechanism in which $A_i = \Theta_i$ for all i and $g(\theta) = f(\theta)$

Definition (Truthuful implementation)

S.c.f. f is truthfully implementable if it can be implemented by a direct revelation mechanism.

Revelation Principle: Statement

Revelation principle (blanket statement)

Suppose there exists a mechanism $\Gamma = (A_1, \ldots, A_N, g)$ that implements the social choice function f.

Then f is truthfully implementable.

- The "theorem" above is informal.
  - "Implementation" requires "an equilibrium", which can mean a million different things.
  - We will now plug in some specific equilibrium concepts.

This slide deck:

Game Theory Recap: Dominant Strategy

- strategy a_i is a full contingent plan of play
- strategy a_i is dominant for agent i if it is best *no matter what the other players do*

Definition (dominant strategy)

Given mechanism $\Gamma = (A, g)$, $a_i : \Theta_i \rightarrow A_i$ is a dominant strategy if for all $\theta_i \in \Theta_i$

$$u_i(g(a_i(\theta_i), a_{-i}), \theta_i) \geq u_i(g(\hat{a}_i, a_{-i}), \theta_i)$$

for all $\hat{a}_i \in A_i$ and all $a_{-i} \in A_{-i}$.

- our definition slightly different from the standard – does not require strict inequality

Dominant Strategy Equilibrium

- in a dominant strategy equilibrium every player plays a dominant strategy

Definition (dominant strategy equilibrium)

A strategy profile $(a_1^*, \ldots, a_N^*)$ is a dominant strategy equilibrium of mechanism $\Gamma = (A_1, \ldots, A_N, g)$ if for all i and all $\theta_i \in \Theta_i$

$$u_i(g(a_i^*(\theta_i), a_{-i}), \theta_i) \geq u_i(g(\hat{a}_i, a_{-i}), \theta_i)$$

for all $\hat{a}_i \in A_i$ and all $a_{-i} \in A_{-i}$.

Now let's finally be formal about all our definitions.

Dominant Strategy Implementation

- A mechanism implements f in dominant strategies if
  - the game induced by the mechanism has a dominant strategy equilibrium
  - the outcome in this equilibrium coincides with f

Definition (implementation in dominant strategies)

A mechanism $\Gamma = (A_1, \ldots, A_N, g)$ implements the social choice function f in dominant strategies if there exists a dominant strategy equilibrium $(a_1^*, \ldots, a_N^*)$ of Γ such that $g(a_1^*(\theta_1), \ldots, a_N^*(\theta_N)) = f(\theta)$ for all $\theta \in \Theta$.

Good Implementation Concept?

- very robust equilibrium concept
    - no need to predict what the other players will play
    - no need to know the type distribution ϕ
    - works even if
        - players don't know ϕ or even if players believe in different ϕ_i (protects from players' model misspecification)
        - players think that other players are not rational
- not a panacea
    - does not rule out other weird Nash Equilibria (example: second-price auction)
    - is not necessarily collusion-proof
    - does not protect from designer's model misspecification

Bottom line: it's as good as they get, but far from perfect.

Dominant Strategy Incentive Compatibility

Theorem (Revelation Principle for Dominant Strategies)

Suppose there exists a mechanism $\Gamma = (A_1, \ldots, A_N, g)$ that implements the social choice function f in dominant strategies.
Then f is truthfully implementable in dominant strategies.

Definition (Dominant Strategy Incentive Compatibility)

"f is dominant strategy incentive compatible (DSIC)"
means the exact same thing as
"f is truthfully implementable in dominant strategies".

DS Revelation Principle: Proof

Let Γ implement f in dominant strategies, i.e. there is a strategy profile $(a_1^*, \ldots, a_N^*)$ such that $g(a_1^*(\theta_1), \ldots, a_N^*(\theta_N)) = f(\theta)$ for all θ, and for all i and $\theta_i \in \Theta_i$,

$$u_i(g(a_i^*(\theta_i), a_{-i}), \theta_i) \geq u_i(g(\hat{a}_i, a_{-i}), \theta_i)$$

for all $\hat{a}_i \in A_i$ and all $a_{-i} \in A_{-i}$.

Then

$$u_i(g(a_i^*(\theta_i), a_{-i}^*(\theta_{-i})), \theta_i) \geq u_i(g(a_i^*(\hat{\theta}_i), a_{-i}^*(\theta_{-i})), \theta_i)$$

for all $\hat{\theta}_i \in \Theta_i$, $\theta_{-i} \in \Theta_{-i}$.

Since $g(a^*(\theta)) = f(\theta)$,

$$u_i(f(\theta_i, \hat{\theta}_{-i}), \theta_i) \geq u_i(f(\hat{\theta}_i, \hat{\theta}_{-i}), \theta_i)$$

for all $\hat{\theta}_{-i} \in \Theta_{-i}$.

Revelation Principle: Is it cool or is it cool?

- Idea: to solve the problem mathematically, it is enough to only look at direct mechanisms!

    - This result allows to quickly check whether a given f is [DS] implementable.
    - If yes, gives you a mechanism to implement it.
    - If not, helps you describe a set of implementable s.c.f. and pick second best.
    - *Yours today for ~~only $49.99 + shipping~~ FREE with a qualifying Mechanism Design course!*

- Translating that solution to the real world may (and often does) result in an indirect mechanism! We'll see some examples.

This slide deck:

DSIC vs BIC

- We've looked at DS implementation so far. Robust but demanding. Can we get more mileage by relaxing the equilibrium notion?
- Now: use standard Bayes-Nash Equilibrium as solution concept. Weaker equilibrium concept, so:
  - we are less confident it will produce the intended outcome, but
  - it can implement more(?) s.c.f-ns.
  - (there's a literature studying whether sets of DSIC and BIC s.c.f-ns are equal in special settings)

Bayesian Implementation

Start with the general model as before:

- N agents;

- set of alternatives X;

- type $\theta_i \in \Theta_i$ is private information of i;

- common prior belief $\phi \in \Delta(\Theta)$ about distribution of types;

- utility functions $u_i(x, \theta_i)$;

- each agent uses Bayes' rule to form a belief over other agents' types

$$\phi(\theta_{-i}|\theta_i) = \phi(\theta_i, \theta_{-i}|\theta_i) = \frac{\phi(\theta_i, \theta_{-i})}{\int_{\tilde{\theta}_{-i} \in \Theta_{-i}} \phi(\theta_i, \tilde{\theta}_{-i}) d\tilde{\theta}_{-i}}.$$

Bayes-Nash Equilibrium

Definition (Bayes-Nash equilibrium)

The strategy profile $a^* = (a_1^*, \ldots, a_N^*)$ with $a_i^* : \Theta_i \to A_i$ is a Bayes-Nash equilibrium of the mechanism $\Gamma = (A_1, \ldots, A_N, g)$ if, for all i and all $\theta_i \in \Theta_i$,

$$\mathbb{E}_{\theta_{-i}} \left[u_i(g(a_i^*(\theta_i), a_{-i}^*(\theta_{-i})), \theta_i)|\theta_i \right] \geq \mathbb{E}_{\theta_{-i}} \left[u_i(g(\hat{a}_i, a_{-i}^*(\theta_{-i})), \theta_i)|\theta_i \right]$$

for all $\hat{a}_i \in A_i$.

- Standard NE reasoning: if everyone else plays eqm strats, i has no incentive to deviate.

- (This definition is for pure strategies, but there is no problem in allowing mixed strategies.)

- Expectations are taken w.r.t. distribution $F(\theta)$

Bayesian Implementation

Definition (Bayesian implementation)

Mechanism $\Gamma = (A_1, \ldots, A_N, g)$ implements s.c.f. f in Bayes-Nash equilibrium if there is a BNE $a^* = (a_1^*, \ldots, a_N^*)$ of Γ such that $f(\theta) = g(a^*(\theta))$ for all $\theta \in \Theta$.

Definition (Bayesian implementability)

S.c.f. f is implementable in BNE if there exists Γ which implements it in BNE.

Truthful Bayesian Implementation

Definition (Truthful Bayesian implementation)

S.c.f. f is truthfully implementable in BNE (=Bayesian Incentive Compatible, BIC) if $a_i^*(\theta_i) = \theta_i$ is a BNE of the direct revelation mechanism $\Gamma = (\Theta_1, \ldots, \Theta_N, f)$.

That is, for all i, θ_i, and $\hat{\theta}_i \in \Theta_i$,

$$\mathbb{E}_{\theta_{-i}}\left[u_i(f(\theta_i, \theta_{-i}), \theta_i)|\theta_i\right] \geq \mathbb{E}_{\theta_{-i}}\left[u_i(f(\hat{\theta}_i, \theta_{-i}), \theta_i)|\theta_i\right].$$

Every player is asked for their type; reporting truthfully is a BNE.

Revelation principle

Theorem (Revelation principle for Bayes-Nash equilibrium)

If there exists a mechanism $\Gamma = (A_1, \ldots, A_N, g)$ that implements f in BNE, then f is truthfully implementable in BNE.

The proof is pretty much the same as for DSIC.